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Miyazawa

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(54) **FINGER ASSIST DEVICE**

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(58) **Field of Classification Search**

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See application file for complete search history.

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(57) **ABSTRACT**

A finger assist device is formed by rotatably connecting a plurality of units in a finger bending direction and a finger spreading direction. The unit is worn on a finger by nipping the finger with a nipping part from the pad and the back of the finger, and a drive force is controlled by detecting a first contact force between the finger pad and the nipping part and a second contact force between the finger back and the nipping part. Since the intention of the wearer of the finger assist device appears in the first contact force and the second contact force, the drive force of the finger assist device is appropriately controlled according to the wearer's intention, and thereby, bending and spreading of the finger may be appropriately assisted.

17 Claims, 10 Drawing Sheets